

CS150 APL: Effects

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- Thursday (Oct 2): project proposal presentation (15 min)
- Sunday (Oct 5): 1-page project proposal due
 - \LaTeX template on Canvas

- Universal and existential types
- Product and sum types
- Mutable references

Control effects:

- Exceptions
- Algebraic effects
- Continuations

Exceptions

- try-catch in Java and many other languages
- An example in Java:

```
try {  
    // code that may throw an exception  
    ...  
    throw ex;  
    ...  
} catch (Exception e) {  
    // handler for Exception  
}
```

Syntax

n	\in	\mathbb{N}	
v	$::=$	$n \mid \lambda x.t$	values
t	$::=$	$n \mid x \mid \lambda x.t \mid t_1 t_2 \mid t_1 \oplus t_2$	terms
		$\mid \text{throw } v \mid \text{try } t_1 \text{ catch } x. t_2$	

Dynamics (first attempt)

$E ::= \square \mid v E \mid E t \mid v \oplus E \mid E \oplus t$ **reduction contexts**
 $\mid \text{try } E \text{ catch } x. t$

$$\frac{}{(\lambda x. t) v \rightarrow t[x := v]} \beta_v$$

$$\frac{}{n_1 \oplus n_2 \rightarrow n_1 + n_2} \text{ADD}$$

$$\frac{}{\text{try } v \text{ catch } x. t \rightarrow v} \text{RETURN}$$

$$\frac{}{\text{try } E[\text{throw } v] \text{ catch } x. t \rightarrow t[x := v]} \text{CATCH}$$

$$\frac{t_1 \rightarrow t'_1}{E[t_1] \rightarrow E[t'_1]} \text{CTX}$$

Example:

```
try {  
    try { throw 42 } catch x. { x + 1 }  
} catch y. { y + 2 }
```


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```

Problem: ambiguous decomposition of E!

Dynamics

$E ::= \square \mid v E \mid E t \mid v \oplus E \mid E \oplus t$ **local contexts**
 $E_h ::= \square \mid v E_h \mid E_h t \mid v \oplus E_h \mid E_h \oplus t$ **handler contexts**
 $\quad \mid \text{try } E_h \text{ catch } x. t$

$$\frac{}{(\lambda x. t) v \rightarrow t[x := v]} \beta_v$$

$$\frac{}{n_1 \oplus n_2 \rightarrow n_1 + n_2} \text{ADD}$$

$$\frac{}{\text{try } v \text{ catch } x. t \rightarrow v} \text{RETURN}$$

$$\frac{}{\text{try } E[\text{throw } v] \text{ catch } x. t \rightarrow t[x := v]} \text{CATCH}$$

$$\frac{t_1 \rightarrow t'_1}{E_h[t_1] \rightarrow E_h[t'_1]} \text{CTX}_h$$

Example:

```
    try { try { 10+(throw 42) } catch x. { x + 1 } } catch y. { y + 2 }  
    /* Catch */  
-> try { 42 + 1 } catch y. { y + 2 }  
    /* Return */  
->* 43
```

- Error recovery: what if we want to recover from an error and continue?

Resumable Exceptions

- Generalization of exceptions: `catch` also binds a “resumption” that can be invoked to resume the computation where the effect was raised.

```
try {  
  val x = throw v;  
  // using x  
  ...  
} catch x,k. {  
  ...  
  k(v)  
}
```

- This idea is known as **algebraic effects and handlers**; expressive and modular way to write effectful programs.
- Mainstream languages such as OCaml 5 have adopted effects handlers.

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- Mainstream languages such as OCaml 5 have adopted effects handlers.
- Demo: the Eff language

- Expressiveness: powerful control abstraction
 - nondeterminism, backtracking
 - mutable states
 - coroutines, async/await
 - etc.
- Modularity:
 - Allow flexible user-defined effect operations
 - Handlers are defined separately
 - Composing multiple effects and handlers is easy

- A fine-grained call-by-value lambda calculus with algebraic effects and handlers

Syntax

$$n \in \mathbb{N}$$
$$v ::= n \mid x \mid \lambda x. t \quad \text{values}$$
$$t ::= v \mid \text{return } v \mid v_1 v_2 \mid \text{let } x = t_1 \text{ in } t_2 \quad \text{computations}$$
$$\mid \text{do } v \mid \text{handle } t \text{ with } x.t_1; x, k.t_2$$

Dynamics

$F ::= \square \mid \text{let } x = F \text{ in } t$

pure contexts

$E ::= \square \mid \text{let } x = E \text{ in } t \mid \text{handle } E \text{ with } x.t_1; x, k.t_2$

general contexts

$$\frac{}{(\lambda x.t) v \rightarrow t[x := v]} \beta_v$$

$$\frac{}{\text{let } x = \text{return } v \text{ in } t \rightarrow t[x := v]} \text{LET}$$

$$\frac{}{\text{handle } (\text{return } v) \text{ with } x.t_1; x, k.t_2 \rightarrow t_1[x := v]} \text{RETURN}$$

$$\frac{f = \lambda y. \text{handle } F[\text{return } y] \text{ with } x.t_1; x, k.t_2}{\text{handle } F[\text{do } v] \text{ with } x.t_1; x, k.t_2 \rightarrow t_2[x := v, k := f]} \text{HANDLE}$$

Example:

```
handle {  
  let x = do 2 in  
  let y = do 3 in  
  return (x + y)  
} with {  
  x => return x  
  x,k => k(x * 2)  
}
```

Example:

```
handle {  
  let x = do 2 in  
  let y = do 3 in  
  return (x + y)  
} with {  
  x => return x  
  x,k => k(x * 2)  
}
```

```
      k(x * 2)  
where  
  x = 2  
  k = \z. handle {  
    let x = return z in  
    let y = do 3 in  
    return (x + y)  
  } with {  
    x => return x  
    x,k => k(x * 2)  
  }
```

Example (cont'd):

```
handle {  
  let x = return 4 in  
  let y = do 3 in  
  return (x + y)  
} with {  
  x => return x  
  x,k => k(x * 2)  
}
```

```
handle {  
  let y = do 3 in  
  return (4 + y)  
} with {  
  x => return x  
  x,k => k(x * 2)  
}
```

Further reading

- Tutorial: *An Introduction to Algebraic Effects and Handlers*. Matija Pretnar
<https://www.eff-lang.org/handlers-tutorial.pdf>

- Theory: Why “algebraic”? Because effects can be modeled using algebraic theories.

What is algebraic about algebraic effects and handlers? Andrej Bauer
<https://arxiv.org/abs/1807.05923>

- Implementation: CEK-style abstract machine for algebraic effects and handlers.
Liberating Effects with Rows and Handlers. Hillerstrom and Lindley. TyDE '16

- Effect handlers captures “delimited continuations” (i.e. rest of computation up to nearest handler).
- A family of general delimited control operators:
 - `shift/reset` (Abstracting Control, Danvy and Filinski)
 - `control/prompt` (The theory and practice of first-class prompts, Felleisen)
 - `shift0/reset0` and `control0/prompt0` (Shift to Control, Shan)
- You can try them in Racket!

A λ -calculus with `shift`/`reset`:

Syntax and dynamics

$t ::= \mid x \mid \lambda x.t \mid t_1 t_2 \mid \langle t \rangle \mid \text{shift } k.t$	terms
$E ::= \square \mid v E \mid E t \mid \langle E \rangle$	reduction contexts

$\frac{}{(\lambda x.t) v \rightarrow t[x := v]} \beta_v$	$\frac{}{\langle v \rangle \rightarrow v} \text{RESET}$
$\frac{E \text{ does not contain } \langle \cdot \rangle}{\langle E[\text{shift } k.t] \rangle \rightarrow t[k := \lambda x. \langle E[x] \rangle]} \text{SHIFT}$	$\frac{t_1 \rightarrow t'_1}{E[t_1] \rightarrow E[t'_1]} \text{CTX}$

- Some cool applications of algebraic effects and delimited continuations:
 - Backtracking and search
 - Concurrency and lightweight threads
 - Probabilistic programming
 - Quantum simulation
Scheme Pearl: Quantum Continuations. (Scheme workshop 2022)
 - Autodifferentiation and backpropagation
Demystifying differentiable programming: shift/reset the penultimate backpropagator (ICFP '19)
 - ...

Delimited Continuations

```
import scala.util.continuations._
type diff = cps[Unit]

class Num(val x: Double, var d: Double) {
  def +(that: Num) = shift { (k: Num => Unit) =>
    val y = new Num(x + that.x, 0.0); k(y)
    this.d += y.d; that.d += y.d }
  def *(that: Num) = shift { (k: Num => Unit) =>
    val y = new Num(x * that.x, 0.0); k(y)
    this.d += that.x * y.d; that.d += this.x * y.d }
}

def grad(f: Num => Num @diff)(x: Double) = {
  val x1 = new Num(x, 0.0)
  reset { f(x1).d = 1.0 }
  x1.d
}

for (x <- 0 until 10) {
  assert(grad(x => x + x*x*x)(x) == 1 + 3*x*x)
}
```

- We can also have undelimited first-class continuations (i.e. rest of computation up to the program end), `call/cc` in Scheme.
- Such continuations are not composable:

```
(+ 1 (call/cc (lambda (k) (begin (k 2) (k 3)))))
```

- Expressiveness: `call/cc` with mutable state can express arbitrary monadic effects and delimited continuations (Representing Monads, Filinski 1994).

- Exceptions
- Resumable exceptions (aka effect handlers)
- A family of delimited control operators
- First-class undelimited continuations
- Other considerations:
 - One-shot vs multi-shot continuations
 - Type systems ensure all effects are handled
 - Effect polymorphism
 - ...