

CS150 APL: Type Systems

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- How to define a programming language?

Syntax and dynamics

$$n \in \mathbb{N}$$

$$t ::= n \mid x \mid \lambda x.t \mid t_1 t_2 \mid t_1 \oplus t_2 \quad \textbf{terms}$$

$$E ::= \square \mid v E \mid E t \mid v \oplus E \mid E \oplus t \quad \textbf{reduction contexts}$$

$$\frac{}{(\lambda x.t) v \rightarrow t[x := v]} \beta_v$$

$$\frac{}{n_1 \oplus n_2 \rightarrow n_1 + n_2} \text{ADD}$$

$$\frac{t_1 \rightarrow t'_1}{E[t_1] \rightarrow E[t'_1]} \text{CTX}$$

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Stuck programs

- Application of a number to another number: $1\ 2$
- Adding a λ -term with a number: $(\lambda x.x) + 3$

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-
- There are well-formed (i.e. syntactically valid) programs that do not evaluate to a value according to the dynamics (i.e. they stuck).
 - We want to rule out such programs statically (i.e. before running them).

- Type system: a syntactic discipline to classify the result of terms (i.e. values)
- *Well-typed programs cannot “go wrong”*. – Robin Milner, 1978

Simply-typed λ -calculus (STLC)

Syntax

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$v ::= n \mid \lambda x.t$ **values**

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$\tau ::= \mathbf{nat} \mid \tau_1 \rightarrow \tau_2$ **types**

$\Gamma ::= \cdot \mid \Gamma, x : \tau$ **type environment**

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Statics

$$\frac{}{\Gamma \vdash n : \text{nat}} \text{NUM}$$

$$\frac{\Gamma(x) = \tau}{\Gamma \vdash x : \tau} \text{VAR}$$

$$\frac{\Gamma, x : \tau_1 \vdash t : \tau_2}{\Gamma \vdash \lambda x. t : \tau_1 \rightarrow \tau_2} \text{ABS}$$

$$\frac{\Gamma \vdash t_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma \vdash t_2 : \tau_1}{\Gamma \vdash t_1 t_2 : \tau_2} \text{APP}$$

$$\frac{\Gamma \vdash t_1 : \text{nat} \quad \Gamma \vdash t_2 : \text{nat}}{\Gamma \vdash t_1 \oplus t_2 : \text{nat}} \text{ADD}$$

Simply-typed λ -calculus (STLC)

- Example

$$\frac{\frac{\Gamma = f : \tau \rightarrow \tau, x : \tau \quad \Gamma(f) = \tau \rightarrow \tau}{f : \tau \rightarrow \tau, x : \tau \vdash f : \tau \rightarrow \tau} \text{VAR} \quad \frac{\Gamma = f : \tau \rightarrow \tau, x : \tau \quad \Gamma(x) = \tau}{f : \tau \rightarrow \tau, x : \tau \vdash x : \tau} \text{VAR}}{f : \tau \rightarrow \tau, x : \tau \vdash f x : \tau} \text{APP}$$
$$\frac{f : \tau \rightarrow \tau, x : \tau \vdash f x : \tau}{f : \tau \rightarrow \tau \vdash \lambda x. f x : \tau \rightarrow \tau} \text{ABS}$$
$$\frac{f : \tau \rightarrow \tau \vdash \lambda x. f x : \tau \rightarrow \tau}{\vdash \lambda f. \lambda x. f x : (\tau \rightarrow \tau) \rightarrow \tau \rightarrow \tau} \text{ABS}$$

- Annotation for argument type: $\lambda x : \tau. t$ (Church-style) vs $\lambda x. t$ (Curry-style)

- Example: $(\lambda x. \lambda y. x \oplus y) 42$

Progress

If $\Gamma \vdash t : \tau$, then either t is a value or there exists a term t_2 such that $t \rightarrow t_2$.

Preservation

If $\Gamma \vdash t : \tau$ and $t \rightarrow t'$, then $\Gamma \vdash t' : \tau$.

Significance

- In real programming languages, it means ruling out certain runtime errors.
- Behaviors that are *not* defined by the dynamic semantics (aka UB, undefined behavior), such as dereferencing a dangling pointer, etc.

Typically, type systems are incomplete: Not all well-behaved programs are well-typed.

Consider extension to STLC:

Syntax, dynamics, and statics

$t ::= \dots \mid \text{if0 } t_1 \ t_2 \ t_3$ **terms**

...

$$\frac{}{\text{if0 } 0 \ t_2 \ t_3 \rightarrow t_2} \text{IF0-THEN} \qquad \frac{}{\text{if0 } n \ t_2 \ t_3 \rightarrow t_3} \text{IF0-ELSE}$$
$$\frac{\Gamma \vdash t_1 : \text{nat} \quad \Gamma \vdash t_2 : \tau \quad \Gamma \vdash t_3 : \tau}{\Gamma \vdash \text{if0 } t_1 \ t_2 \ t_3 : \tau} \text{IF0}$$

- What would be a well-behaved but untypable program?

Simply-typed λ -calculus (STLC) with division

- Can we capture all possible runtime errors with a type system?

Syntax and dynamics

$t ::= \dots \mid t_1 \text{ div } t_2$ **terms**

...
$$\frac{}{n_1 \text{ div } n_2 \rightarrow n_1/n_2} \text{DIV}$$

Simply-typed λ -calculus (STLC) with division

- Can we capture all possible runtime errors with a type system?

Syntax and dynamics

$t ::= \dots \mid t_1 \text{ div } t_2$ **terms**

\dots
$$\frac{}{n_1 \text{ div } n_2 \rightarrow n_1/n_2} \text{DIV}$$

Options:

- Enhance the type system to rule out division by zero statically
 - Needs to analyze possible numeric values, possible but would rule out many good programs too
- Change the dynamic semantics to include runtime checks, so that $n/0 \rightarrow err$
 - Add a value representation *err* checked runtime errors
 - Runtime overhead

- Declarative type system
 - Read type judgment as a relation: $(\Gamma, t, \tau) \in \mathcal{T}$
 - Describe a set of triples (i.e. relation) of type environment, term, and type
 - Can be nondeterministic (i.e. multiple rules can apply)
- Algorithmic type checking/inference
 - Describe an algorithm to decide given a term t if $(\Gamma, t, \tau) \in \mathcal{T}$
 - Usually syntax-directed, avoiding backtracking
 - Could require type annotations from users to be decidable

- How to write a generic identity function that works for all types?
- $\vdash \lambda x : \tau. x : \tau \rightarrow \tau$ only defines for a specific τ (note that τ is a meta variable here).

- How to write a generic identity function that works for all types?
- $\vdash \lambda x : \tau. x : \tau \rightarrow \tau$ only defines for a specific τ (note that τ is a meta variable here).
- Polymorphism: enables writing generic code that works for values of different types
 - Example: traverse a list but you don't care about the type of elements in the list, such as `map/fold` function in functional programming languages
 - Generics in Java, C#, etc.

- System F (also called the polymorphic λ -calculus) extends STLC with universal types (aka. parametric polymorphism).
- Idea: introduce universal quantification over types.
- Just as we have λ -terms that abstract over terms, we have Λ -terms that abstract over types.

Syntax

$n \in \mathbb{N}$

$t ::= n \mid x \mid \lambda x : \tau. t \mid t_1 t_2 \mid t_1 \oplus t_2 \mid \Lambda \alpha. t \mid t \tau$ **terms**

$v ::= n \mid \lambda x : \tau. t \mid \Lambda \alpha. t$ **values**

$E ::= \square \mid v E \mid E t \mid v \oplus E \mid E \oplus t \mid E \tau$ **reduction contexts**

$\tau ::= \text{nat} \mid \tau_1 \rightarrow \tau_2 \mid \alpha \mid \forall \alpha. \tau$ **types**

$\Gamma ::= \cdot \mid \Gamma, x : \tau \mid \Gamma, \alpha$ **type environment**

Dynamics

$$\dots \quad \frac{}{(\lambda x : \tau. t) v \rightarrow t[x := v]} \beta_v \quad \frac{}{(\Lambda \alpha. t) \tau \rightarrow t[\alpha := \tau]} \beta_\Lambda$$

- Example:

type application $(\Lambda \alpha. \lambda x : \alpha. x) \text{ nat} \rightarrow (\lambda x : \alpha. x)[\alpha := \text{nat}] \equiv \lambda x : \text{nat}. x$

Statics

$$\dots \quad \frac{\Gamma, \alpha \vdash t : \tau}{\Gamma \vdash \Lambda \alpha. t : \forall \alpha. \tau} \text{TAbs}$$

$$\frac{\Gamma \vdash t : \forall \alpha. \tau_1}{\Gamma \vdash t \tau_2 : \tau_1[\alpha := \tau_2]} \text{TApp}$$

Example: Church-encoded Booleans

- Type of Booleans: $\forall \alpha. \alpha \rightarrow \alpha \rightarrow \alpha$
- True: $\Lambda \alpha. \lambda t : \alpha. \lambda f : \alpha. t$
- False: $\Lambda \alpha. \lambda t : \alpha. \lambda f : \alpha. f$
- if t_1 then t_2 else t_3 : $X \triangleq t_1 \ X \ t_2 \ t_3$

Example: Church-encoded Booleans

- Example: if true then 1 else 2

$$= (\Lambda\alpha.\lambda t : \alpha.\lambda f : \alpha.t) \text{ nat } 1 \ 2$$

$$\rightarrow (\lambda t : \text{nat}.\lambda f : \text{nat}.t) \ 1 \ 2$$

$$\rightarrow (\lambda f : \text{nat}.1) \ 2$$

$$\rightarrow 1$$

- Unit type
- Product type
- Sum type

- Syntax

$$\begin{array}{lll} t & ::= & \dots \mid () \quad \textbf{terms} \\ v & ::= & \dots \mid () \quad \textbf{values} \\ \tau & ::= & \dots \mid \text{unit} \quad \textbf{types} \end{array}$$

- Dynamics: no reduction
- Statics:

$$\frac{}{\Gamma \vdash () : \text{unit}} \text{UNIT}$$