

# CS107: Improved CPS Translation and Other IRs

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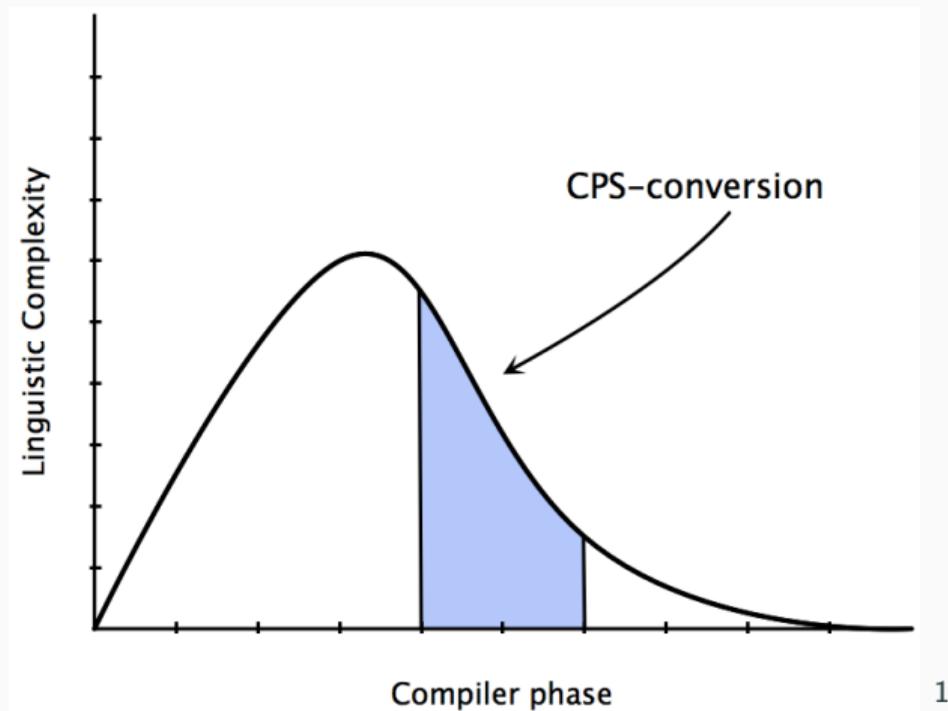
February 10, 2026

Spring 2026

Tufts University

- Review the CPS translation
- Improve the CPS translation
- SSA-based IRs

# Recap



<sup>1</sup>Image credit: <https://matt.might.net/articles/cps-conversion/>

## Selected Rules for CPS Translation

The translation function:

$$\llbracket \cdot \rrbracket : \text{MSTree} \Rightarrow (\text{Symbol} \Rightarrow \text{CPSTree}) \Rightarrow \text{CPSTree}$$

Example:

$$\llbracket t \rrbracket c : \text{CPSTree}$$

where  $t : \text{MSTree}$  and  $c : \text{Symbol} \Rightarrow \text{CPSTree}$

Key ideas:

- Translation under a context, the “result” will be plugged into the context
- Context (aka continuation) is represented as a function in the meta-language
- Translation follows the evaluation order

## Selected Rules for CPS Translation

$\llbracket n \rrbracket C = C[n]$  where  $n$  is an identifier for immutable variable

$\llbracket l \rrbracket C = \text{val}_l \underline{n} = l; C[n]$  where  $l$  is a literal

$\llbracket \text{val } n_1 = e_1; e \rrbracket C =$   
 $\llbracket e_1 \rrbracket (\lambda v (\text{val}_p n_1 = \text{id}(v); \llbracket e \rrbracket C))$

$\llbracket \text{var } n_1 = e_1; e \rrbracket C =$   
 $\text{val}_l \underline{s} = 1;$   
 $\text{val}_p n_1 = \text{block-alloc-var}(s);$   
 $\text{val}_l \underline{z} = 0;$   
 $\llbracket e_1 \rrbracket (\lambda v (\text{val}_p \underline{d} = \text{block-set}(n_1, z, v); \llbracket e \rrbracket C))$

$\llbracket n_1 = e_1 \rrbracket C =$   
 $\text{val}_l \underline{z} = 0;$   
 $\llbracket e_1 \rrbracket (\lambda v (\text{val}_p \underline{d} = \text{block-set}(n_1, z, v); C[v] ))$

## Selected Rules for CPS Translation

$\llbracket n \rrbracket C =$   
   $\text{val}_l \underline{z} = 0;$   
   $\text{val}_p \underline{v} = \text{block-get}(n, z); C[v]$   
  *where  $n$  is an identifier for mutable variable*

$\llbracket \text{def } f_1(n_{1,1}: -, \dots) = e_1; \text{def } \dots ; e \rrbracket C =$   
   $\text{def}_f f_1(\underline{c}, n_{1,1}, \dots) = \{$   
     $\llbracket e_1 \rrbracket (\lambda v(c(v)))$   
   $\};$   
   $\text{def}_f \dots;$   
   $\llbracket e \rrbracket C$

$\llbracket e(e_1, e_2, \dots) \rrbracket C =$   
   $\llbracket e \rrbracket (\lambda v(\llbracket e_1 \rrbracket (\lambda v_1(\llbracket e_2 \rrbracket (\lambda v_2(\dots$   
   $\text{def}_c \underline{c}(r) = \{ C[r] \};$   
   $v(c, v_1, v_2 \dots))))))$

## Example

Let  $k_0$  be the initial context  $\lambda v(\text{val}_l z = 0; \text{halt}(z))$ .

```
[[ f(g(1, 2)) ]] k_0
{ f(g(1, 2)) is a function application }
= [[f]](\lambda v ([[g(1, 2)]] (\lambda v_1
  def_c c_1(r_1) = { k_0[r_1] };
  v(c_1, v_1))))))
= ???
```

## Example

Let  $k_0$  be the initial context  $\lambda v(\text{val}_l z = 0; \text{halt}(z))$ .

```
[[ f(g(1, 2)) ]] k_0
{ f(g(1, 2)) is a function application }
= [[f]](\lambda v(\[[g(1, 2)]](\lambda v_1
  def_c c_1(r_1) = { k_0[r_1] };
  v(c_1, v_1))))))
{ f is an immutable variable }
= [[g(1, 2)]](\lambda v_1
  def_c c_1(r_1) = { k_0[r_1] };
  f(c_1, v_1))
{ let's remember the continuation in the meta-lang as k_1 }
= [[g(1, 2)]] k_1
{ g(1, 2) is a function application }
= [[g]](\lambda v_g(\[[1]](\lambda v_1(\[[2]](\lambda v_2(
  def_c c_2(r_2) = { k_1[r_2] };
  v_g(c_2, v_1, v_2)))))))
{ g is an immutable variable }
```

## Example

```
= [[g]](λvg([[1]](λv1([[2]](λv2(
  defc c2(r2) = { k1[r2] };
  vg(c2, v1, v2))))))
{ g is an immutable variable }
= [[1]](λv1([[2]](λv2(
  defc c2(r2) = { k1[r2] };
  g(c2, v1, v2))))
{ 1 and 2 are literals }
= vall n1 = 1;
  vall n2 = 2;
  defc c2(r2) = { k1[r2] };
  g(c2, n1, n2)
{ inline and apply continuation remembered as k1 }
= vall n1 = 1;
  vall n2 = 2;
  defc c2(r2) = {
    defc c1(r1) = { k0[r1] }; f(c1, r2)
  };
  g(c2, n1, n2)
```

## Example

```
{ inline and apply continuation remembered as  $k_0$  }  
=  
  vall n1 = 1;  
  vall n2 = 2;  
  defc c2(r2) = {  
    defc c1(r1) = { vall z = 0; halt(z) }  
    f(c1, r2)  
  };  
  g(c2, n1, n2)  
{ we are done! }
```

The translation presented before has two shortcomings:

- 1) It produces terms containing useless continuations, and
- 2) It produces suboptimal MiniScala/CPS code for some conditionals.

One solution: define different translations depending on the source (i.e. MiniScala) context surrounding the expression being translated.

## Useless Continuations

The first problem can be illustrated with the MiniScala term:

```
def f(g: () => Int) = g(); f
```

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which in the empty context gets translated to:

```
deff f(c, g) = {  
  defc j(r) = { c(r) };  
  g(j)  
};  
f
```

## Useless Continuations

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which in the empty context gets translated to:

```
deff f(c, g) = {  
  defc j(r) = { c(r) };  
  g(j)  
};  
f
```

instead of the equivalent and more compact:

```
deff f(c, g) = { g(c) };  
f
```

## Suboptimal Conditionals (1)

The second problem can be illustrated with the MiniScala term:

```
if (if (a) b else false) x else y
```

which, in the empty context, gets translated to:

```
defc ci1(v1) = { v1 };  
defc ct1() = { ci1(x) };  
defc cf1() = { ci1(y) };  
vall f1 = false;  
defc ci2(v2) = {  
  if (v2 != f1) ct1 else cf1 };  
defc ct2() = { ci2(b) };  
defc cf2() = {  
  vall i1 = false; ci2(i1) };  
vall f2 = false;  
if (a != f2) ct2 else cf2
```

## Suboptimal Conditionals (2)

A much better translation for:

```
if (if (a) b else false) x else y
```

would be:

```
defc ci1(v1) = { v1 };  
defc ct1() = { ci1(x) };  
defc cf1() = { ci1(y) };  
defc ca1() = {  
  vall i1 = false;  
  if (b != i1) ct1 else cf1 };  
vall i2 = false;  
if (a != i2) ca1 else cf1
```

which immediately applies continuation  $cf_1$  if  $a$  is false.

Common to the two problems: the translation could be better if we translate differently under different source contexts.

- In the first example, the function call could be translated more efficiently since it appears as the *last expression of the function* (i.e. the **tail position**).
- In the second example, the nested **if** expression could be translated more efficiently, since it appears in the condition of another **if** expression and one of its branches is a simple boolean literal (here `false`).

Therefore, instead of having one translation function, we should have several: one per source context worth considering!

## A Better Translation

We split the single translation function into three separate ones:

- 1)  $\llbracket \cdot \rrbracket_N \mathcal{C}$ , taking as before a term to translate and a context  $\mathcal{C}$ , whose hole must be plugged with a *name/symbol* bound to the value of the term.

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- 1)  $\llbracket \cdot \rrbracket_N \mathcal{C}$ , taking as before a term to translate and a context  $\mathcal{C}$ , whose hole must be plugged with a *name/symbol* bound to the value of the term.
- 2)  $\llbracket \cdot \rrbracket_T \mathcal{C}$ , taking a term to translate and a symbol  $\mathcal{C}$  for the continuation. This continuation is to be applied to the value of the term.

## A Better Translation

We split the single translation function into three separate ones:

- 1)  $\llbracket \cdot \rrbracket_N C$ , taking as before a term to translate and a context  $C$ , whose hole must be plugged with a *name/symbol* bound to the value of the term.
- 2)  $\llbracket \cdot \rrbracket_T C$ , taking a term to translate and a symbol  $C$  for the continuation. This continuation is to be applied to the value of the term.
- 3)  $\llbracket \cdot \rrbracket_C ct\ cf$ , taking a term to translate and two parameterless continuations,  $ct$  and  $cf$ . The continuation  $ct$  is to be applied when the term evaluates to a true value, while the continuation  $cf$  is to be applied when it evaluates to a false value.

## The Non-tail Translation

$\llbracket \cdot \rrbracket_N$  is called the **non-tail** translation as it is used in non-tail contexts. That is, when the work that has to be done once the term is evaluated is more complex than simply applying a continuation to the term's value.

For example, the arguments of a primitive are always in a non-tail context, since once they are evaluated, the primitive has to be applied on their value:

```
 $\llbracket p(e_1, e_2, \dots) \rrbracket_N C =$   
 $\llbracket e_1 \rrbracket_N (\lambda v_1 (\llbracket e_2 \rrbracket_N (\lambda v_2 \dots)))$ ;  
 $\text{val}_p \underline{n} = p(v_1, v_2, \dots)$ ;  
 $C[n]$   
where  $p$  is not a logical primitive
```

## The Tail Translation

The tail translation  $\llbracket \cdot \rrbracket_T$  is used whenever the context passed to the simple translation has the form  $\lambda v(c(v))$ . It gets as argument the name of the continuation  $c$  to which the value of expression should be applied.

For example, the previous translation of function definition:

```
 $\llbracket \text{def } f_1(n_{1,1}: \_, \dots) = e_1; \dots ; e \rrbracket_C =$   
 $\text{def}_f f_1(\underline{c}, n_{1,1}, \dots) = \{ \llbracket e_1 \rrbracket(\lambda v(c(v))) \};$   
 $\text{def}_f \dots ;$   
 $\llbracket e \rrbracket_C$ 
```

becomes:

```
 $\llbracket \text{def } f_1(n_{1,1}: \_, \dots) = e_1; \text{def } \dots ; e \rrbracket_N C =$   
 $\text{def}_f f_1(\underline{c}, n_{1,1}, \dots) = \{ \llbracket e_1 \rrbracket_T c \};$   
 $\text{def}_f \dots ;$   
 $\llbracket e \rrbracket_N C$ 
```

## The Cond Translation (1)

The cond translation  $\llbracket \cdot \rrbracket_C$  is used whenever the term to translate is a condition to decide how execution must proceed. It takes two continuations as arguments: the first is to be applied when the condition is true, while the second is to be applied when it is false.

This translation is used to handle the condition of an if expression:

```

$$\llbracket \text{if } (e_1) e_2 \text{ else } e_3 \rrbracket_N C =$$

$$\text{def}_c \underline{c}(r) = \{ C[r] \};$$

$$\text{def}_c \underline{ct}() = \{ \llbracket e_2 \rrbracket_T c \};$$

$$\text{def}_c \underline{cf}() = \{ \llbracket e_3 \rrbracket_T c \};$$

$$\llbracket e_1 \rrbracket_C \underline{ct} \underline{cf}$$

```

## The Cond Translation (2)

Having a separate translation for conditional expressions makes the efficient compilation of conditionals with literals in one of their branch possible:

$$\llbracket \text{if } (e_1) \text{ false else true} \rrbracket_C \text{ ct cf} = \llbracket e_1 \rrbracket_C \text{ cf ct}$$

Intuition: **if** (**if** (a) false **else** true) x **else** y is equivalent to **if** (a) y **else** x.

## The Cond Translation (2)

Having a separate translation for conditional expressions makes the efficient compilation of conditionals with literals in one of their branch possible:

$$\llbracket \text{if } (e_1) \text{ false else true} \rrbracket_C \text{ ct cf} = \llbracket e_1 \rrbracket_C \text{ cf ct}$$

Intuition: **if** (**if** (a) false **else** true) x **else** y is equivalent to **if** (a) y **else** x.

$$\begin{aligned} \llbracket \text{if } (e_1) e_2 \text{ else false} \rrbracket_C \text{ ct cf} = \\ \text{def}_c \underline{c}() = \{ \llbracket e_2 \rrbracket_C \text{ ct cf} \}; \\ \llbracket e_1 \rrbracket_C \underline{c} \text{ cf}; \end{aligned}$$

... and so on for all conditionals with at least one constant branch.

## The Cond Translation (3)

```
[[ while (e1) e2; e3 ]]N C =  
  defc loop(d) = {  
    defc c() = { [[e3]]N C };  
    defc ct() = { [[e2]]T loop };  
    [[e1]]C ct c  
  };  
  vall d = ();  
  loop(d)
```

Translating the following program:

```
def f(g: () => Int) = 42 + g(); f
```

## The Better Translation In Scala

In the compiler, the three translations are simply three mutually-recursive functions, with the following signatures:

```
def nonTail(t: MSTree)  
    (c: Symbol => CPSTree): CPSTree
```

```
def tail(t: MSTree,  
        c: Symbol): CPSTree
```

```
def cond(t: MSTree,  
        ct: Symbol,  
        cf: Symbol): CPSTree
```

- Continuation-passing style (CPS)
- Administrative normal form (ANF)
- Register-transfer language (RTL) and control-flow graph (CFG)
- Static Single-Assignment (SSA) form
- Sea-of-nodes (graph-based) IRs

## IR #2: Standard RTL/CFG - Register-transfer Language

Register-transfer language (RTL):

- Most operations/instructions compute a function using virtual registers (i.e. variables),
- Operations store the result in another virtual register.

Example:  $x \leftarrow y + z$ : adding variables  $y$  and  $z$ , storing the result in  $x$  could be written.

Such instructions are sometimes called quadruples, because they typically have four components: the three variables ( $x$ ,  $y$  and  $z$  here) and the operation ( $+$  here).

RTLs are very close to assembly languages, the main difference being that the number of virtual registers is usually not bounded.

A control-flow graph (CFG) is a directed graph whose nodes are the individual instructions of a function, and whose edges represent control-flow.

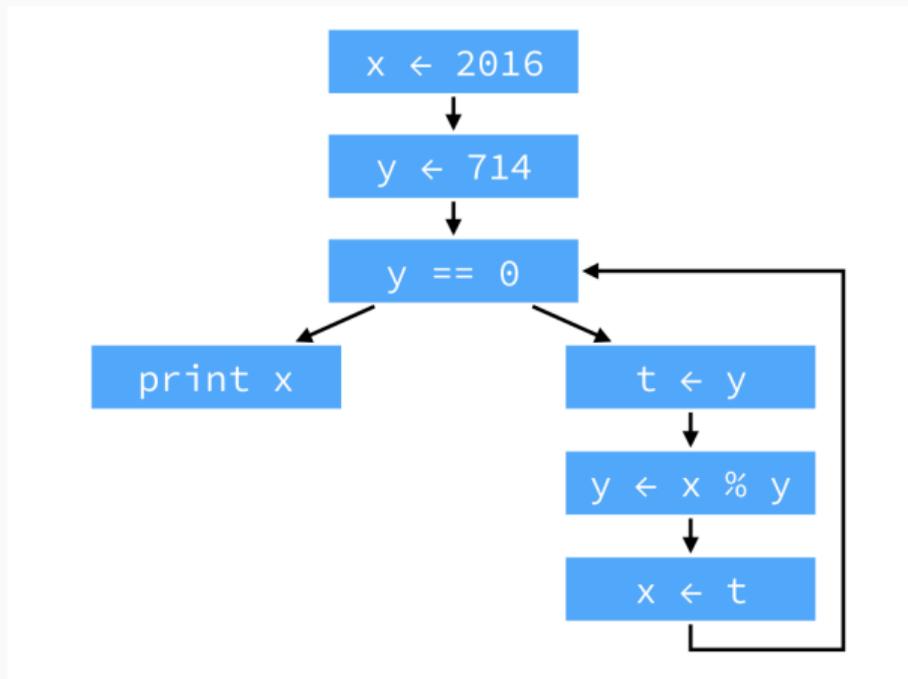
More precisely, there is an edge in the CFG from a node  $n_1$  to a node  $n_2$  if and only if the instruction of  $n_2$  can be executed immediately after the instruction of  $n_1$ .

RTL/CFG is an intermediate representation where each function of the program is represented as a control-flow graph whose nodes contain RTL instructions.

This kind of representation is very common in the later stages of compilers, especially those for imperative languages.

## RTL/CFG Example

Computation of the GCD of 2016 and 714 in a typical RTL/CFG representation.

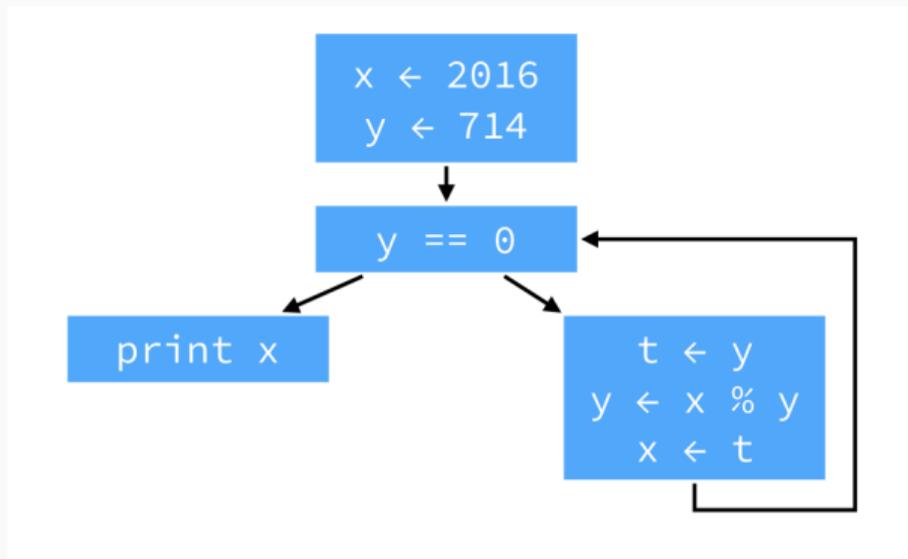


Basic block: a list of instructions that that execute sequentially. Control can only enter through the first instruction of the block and leave through the last.

Basic blocks are often used as the nodes of the CFG, instead of individual instructions. This has the advantage of reducing the number of nodes in the CFG, but also complicates data-flow analyses.

## RTL/CFG Example

The same examples as before, but with basic blocks instead of individual instructions.



Today's lecture:

- Improved CPS translation
- RTL/CFG IR

Next time:

- More on SSA IR
- Value representation